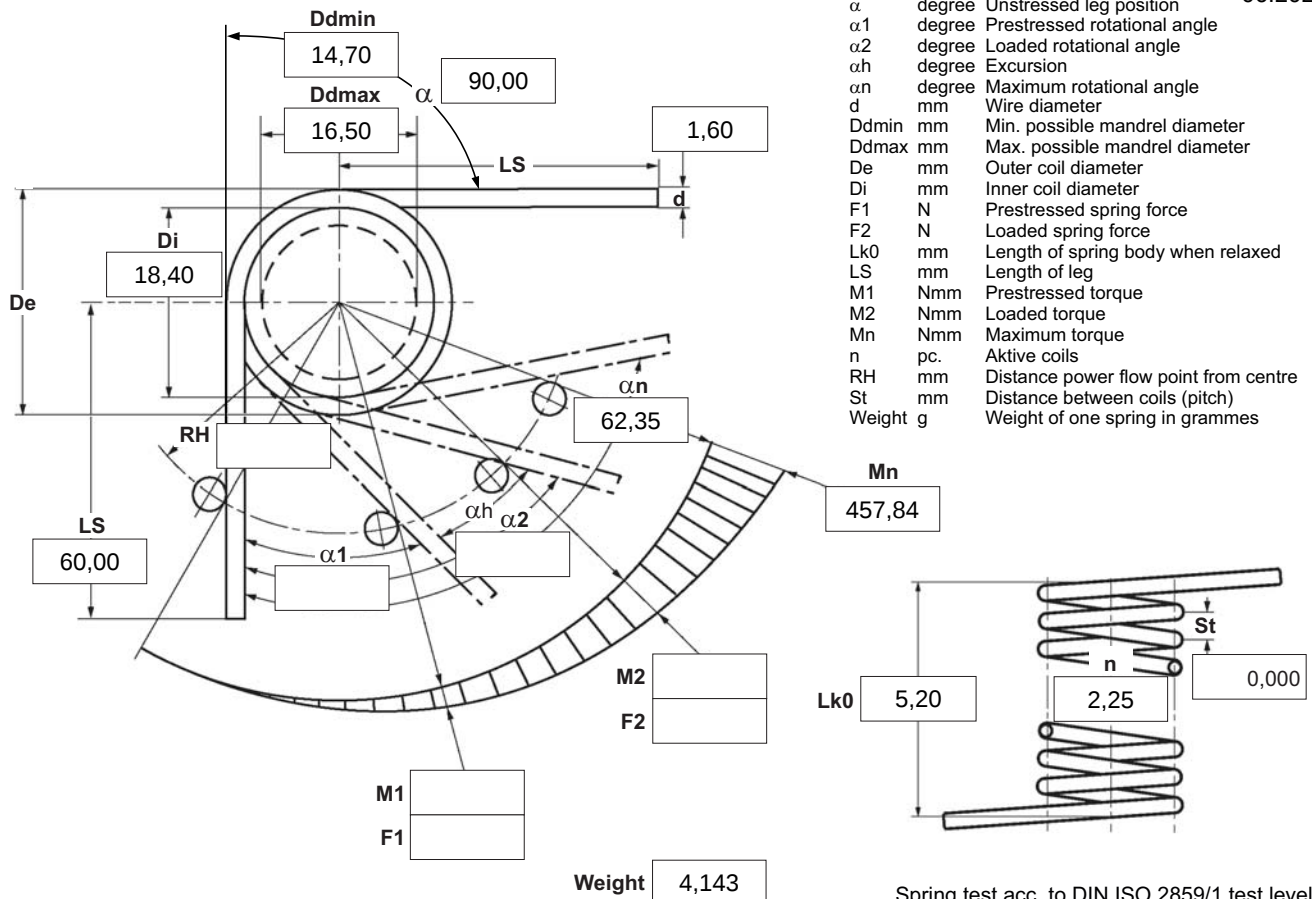


06.2025



Spring test acc. to DIN ISO 2859/1 test level II

1 Coiling direction ☒ left ☐ right	5 Excursion a_h degr.	12 Tolerances to DIN 2194 <table border="1" style="width: 100%; border-collapse: collapse; text-align: center;"> <tr> <th>Grade</th> <th>Di</th> <th>Lk0</th> <th>LSH,LSR</th> <th>$\alpha, \alpha 1, \alpha 2$</th> <th>M1,M2</th> <th>Wire diameter d to DIN 2076</th> </tr> <tr> <td>1</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> <td rowspan="3">☒</td> </tr> <tr> <td>2</td> <td>☒</td> <td>☒</td> <td>☒</td> <td>☒</td> <td>☒</td> </tr> <tr> <td>3</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> </tr> </table>	Grade	Di	Lk0	LSH,LSR	$\alpha, \alpha 1, \alpha 2$	M1,M2	Wire diameter d to DIN 2076	1	☐	☐	☐	☐	☐	☒	2	☒	☒	☒	☒	☒	3	☐	☐	☐	☐	☐
Grade	Di	Lk0	LSH,LSR	$\alpha, \alpha 1, \alpha 2$	M1,M2	Wire diameter d to DIN 2076																						
1	☐	☐	☐	☐	☐	☒																						
2	☒	☒	☒	☒	☒																							
3	☐	☐	☐	☐	☐																							
2 Form of legs tangential, straight, no bends * *We can also supply torsion springs with any form of leg for an extra charge.	6 Stress cyc. end. N	7 Stress cycle frequ. n /																										
3 Fixing Recumbent leg ☐ Lever leg ☐	8 Application temp. °C																											
4 Load ☐ in winding direction ☐ against winding direction	9 Material 1.4310																											
10 Wire or rod surface ☒ drawn ☐ rolled ☐ metal-cut		11 Surface treatment 																										
13 Production compensation through <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td style="width: 80%;">A spring torque and the associated swing angle</td> <td style="width: 20%;">α ☒</td> </tr> <tr> <td rowspan="2">A spring torque and the associated swing angle and α0</td> <td>n, d ☐</td> </tr> <tr> <td>n, Di ☐</td> </tr> <tr> <td rowspan="2">Two spring resistances and the associated swing angle</td> <td>α, n, d ☐</td> </tr> <tr> <td>α, n, Di ☐</td> </tr> </table>			A spring torque and the associated swing angle	α ☒	A spring torque and the associated swing angle and α0	n, d ☐	n, Di ☐	Two spring resistances and the associated swing angle	α, n, d ☐	α, n, Di ☐																		
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Remarks

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