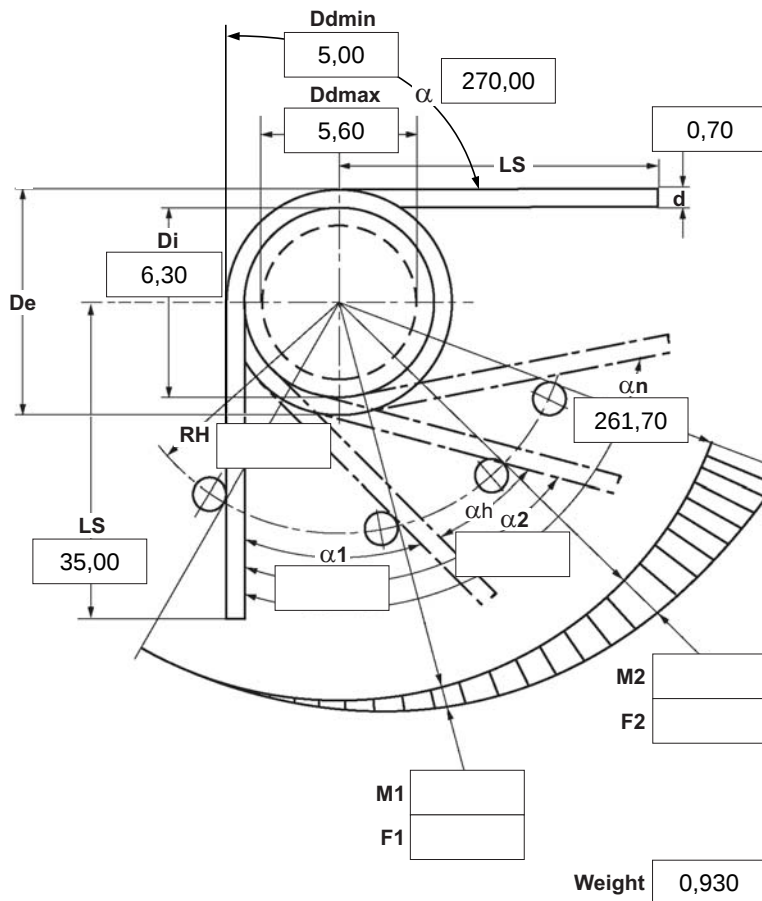
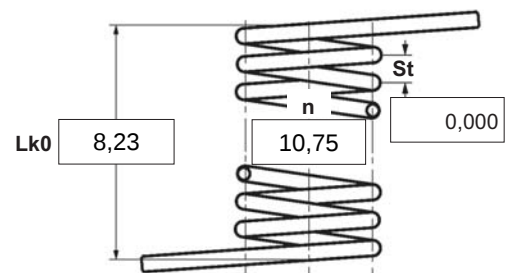


07.2025



α	degree	Unstressed leg position
α_1	degree	Prestressed rotational angle
α_2	degree	Loaded rotational angle
αh	degree	Excursion
αn	degree	Maximum rotational angle
d	mm	Wire diameter
Ddmin	mm	Min. possible mandrel diameter
Ddmax	mm	Max. possible mandrel diameter
De	mm	Outer coil diameter
Di	mm	Inner coil diameter
F1	N	Prestressed spring force
F2	N	Loaded spring force
Lk0	mm	Length of spring body when relaxed
LS	mm	Length of leg
M1	Nmm	Prestressed torque
M2	Nmm	Loaded torque
Mn	Nmm	Maximum torque
n	pc.	Active coils
RH	mm	Distance power flow point from centre
St	mm	Distance between coils (pitch)
Weight	g	Weight of one spring in grammes



Spring test acc. to DIN ISO 2859/1 test level II

1 Coiling direction ☒ left ☐ right	5 Excursion <u>α</u> degr.	12 Tolerances to DIN 2194 <table border="1" style="width: 100%; border-collapse: collapse; text-align: center;"> <tr> <th>Grade</th> <th>Di</th> <th>Lk0</th> <th>LSH,LSR</th> <th>$\alpha, \alpha 1, \alpha 2$</th> <th>M1,M2</th> <th>Wire diameter d to DIN 2076</th> </tr> <tr> <td>1</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> <td rowspan="3">☒</td> </tr> <tr> <td>2</td> <td>☒</td> <td>☒</td> <td>☒</td> <td>☒</td> <td>☒</td> </tr> <tr> <td>3</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> <td>☐</td> </tr> </table>	Grade	Di	Lk0	LSH,LSR	$\alpha, \alpha 1, \alpha 2$	M1,M2	Wire diameter d to DIN 2076	1	☐	☐	☐	☐	☐	☒	2	☒	☒	☒	☒	☒	3	☐	☐	☐	☐	☐
Grade	Di	Lk0	LSH,LSR	$\alpha, \alpha 1, \alpha 2$	M1,M2	Wire diameter d to DIN 2076																						
1	☐	☐	☐	☐	☐	☒																						
2	☒	☒	☒	☒	☒																							
3	☐	☐	☐	☐	☐																							
2 Form of legs tangential, straight, no bends * *We can also supply torsion springs with any form of leg for an extra charge.	6 Stress cyc. end. N	13 Production compensation through <table border="1" style="width: 100%; border-collapse: collapse;"> <tr> <td>A spring torque and the associated swing angle</td> <td>α</td> <td>☒</td> </tr> <tr> <td>A spring torque and the associated swing angle and $\alpha 0$</td> <td>n, d</td> <td>☐</td> </tr> <tr> <td></td> <td>n, Di</td> <td>☐</td> </tr> <tr> <td>Two spring resistances and the associated swing angle</td> <td>α, n, d</td> <td>☐</td> </tr> <tr> <td></td> <td>α, n, Di</td> <td>☐</td> </tr> </table>	A spring torque and the associated swing angle	α	☒	A spring torque and the associated swing angle and $\alpha 0$	n, d	☐		n, Di	☐	Two spring resistances and the associated swing angle	α , n, d	☐		α , n, Di	☐											
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7 Stress cycle frequ. n /	8 Application temp. °C																											
3 Fixing Recumbent leg Lever leg	9 Material 1.4310	Prices <table style="width: 100%;"> <tr> <td style="text-align: right;">Mennyiségi lépcsők</td> <td style="text-align: right;">Egységár (EUR)</td> </tr> <tr> <td style="text-align: right;">1</td> <td style="text-align: right;">5,1100 €</td> </tr> <tr> <td style="text-align: right;">2</td> <td style="text-align: right;">3,6000 €</td> </tr> <tr> <td style="text-align: right;">3</td> <td style="text-align: right;">3,4200 €</td> </tr> </table>	Mennyiségi lépcsők	Egységár (EUR)	1	5,1100 €	2	3,6000 €	3	3,4200 €																		
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1	5,1100 €																											
2	3,6000 €																											
3	3,4200 €																											
4 Load ☐ in winding direction ☐ against winding direction	10 Wire or rod surface ☒ drawn ☐ rolled ☐ metal-cut																											
11 Surface treatment 																												

Remarks

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